

Posterior Inference in Gaussian Processes is an Affine Transformation

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A Gaussian

$$\begin{bmatrix} f_1 \\ f_2 \end{bmatrix} \sim \mathcal{N} \left(\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{12}^T & \Sigma_{22} \end{bmatrix} \right) \quad (1)$$

The Conditional / Posterior Distribution

$$f_1 \mid (f_2 = \hat{f}) \sim \mathcal{N} \left(\mu_1 + \Sigma_{12} \Sigma_{22}^{-1} (\hat{f} - \mu_2), \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{12}^T \right) \quad (2)$$

(Standard result, found in any good statistics / ML textbook).

Affine Transformations of Gaussians

Gaussians are closed under affine transforms; the affine transform of a Gaussian RV is another Gaussian RV.

$$f \sim \mathcal{N}(\mu, \Sigma) \quad (3)$$

$$Pf + q \sim \mathcal{N}(P\mu + q, P\Sigma P^T) \quad (4)$$

(Standard result, found in any good statistics / ML textbook).

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- ▶ Answer: Yes. $P := [\mathcal{I}, -\Sigma_{12}\Sigma_{22}^{-1}]$, $q := \Sigma_{12}\Sigma_{22}^{-1}\hat{f}$.

Same thing?

$$[\mathcal{I}, -\Sigma_{12}\Sigma_{22}^{-1}] \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} + \Sigma_{12}\Sigma_{22}^{-1}\hat{f} = \mu_1 + \Sigma_{12}\Sigma_{22}^{-1}(\hat{f} - \mu_2) \quad (5)$$

$$\begin{bmatrix} \mathcal{I} \\ -\Sigma_{22}^{-1}\Sigma_{12}^T \end{bmatrix}^T \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{12}^T & \Sigma_{22} \end{bmatrix} \begin{bmatrix} \mathcal{I} \\ -\Sigma_{22}^{-1}\Sigma_{12}^T \end{bmatrix} = \Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{12}^T. \quad (6)$$

Conclusion

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- ▶ Gaussians are closed under affine transformations.
- ▶ Posterior inference in a Gaussian (process) RV *is* an affine transformation of the prior.